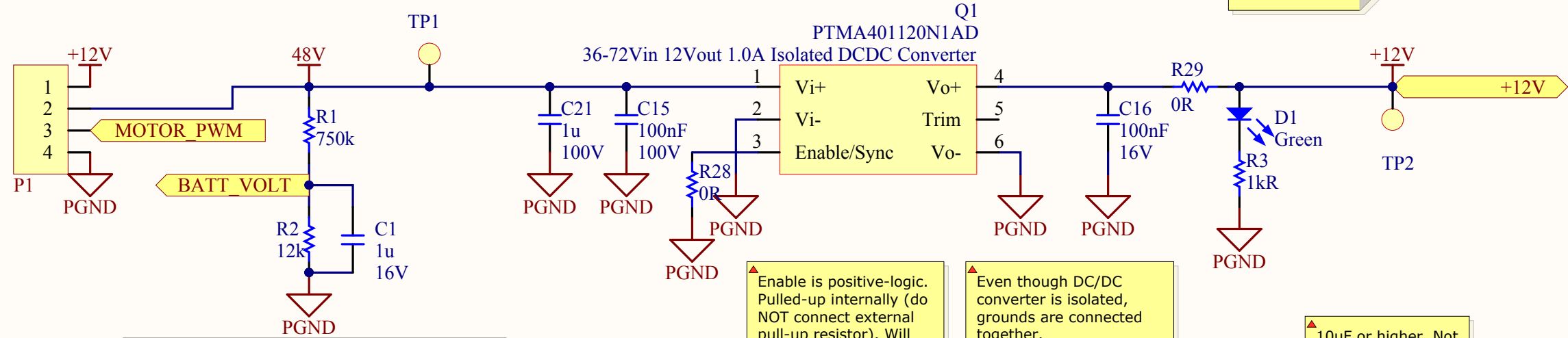


|   |                                  |
|---|----------------------------------|
| Title<br><b>Top Level Design</b>                                      |                                  |
| Document Name<br><b>Top Level.SchDoc</b>                              |                                  |
| Project Name<br><b>Skateboard Motherboard Transceiver v1.1.PrjSCH</b> |                                  |
| Client<br><b>Geo</b>  | Revision<br><b>v1.1</b>          |
| Company Name<br><b>CladLabs</b>                                       | Modified Date<br><b>7/1/2012</b> |
| Drawn By<br><b>Geoffrey Hunter</b>                                    |                                  |

▲ Battery input. Rated nominal voltage is 48V, but normally sits around 53V. Can get up to 60V when charging.

Comes from motor controller board, 12V supply and PWM signal for motor controller also sent back in the same connector.



▲ Power indication LED. Designed for 10mA @ 12V bus.

▲ ADC input cannot exceed 3.3V when input is at it's maximum of 60V.

Vout = 945mV when Vin=60V. C1 for stability.

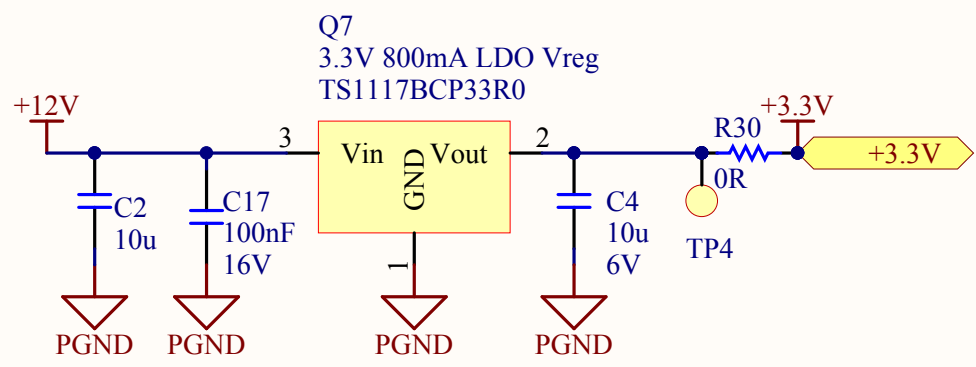
Also, care has to be taken to make sure that the micro's ESD diodes don't conduct more than 100uA at start-up. Worst case is 60V on rail and micro supply still at 0, pulling BATT\_VOLT to 0.7V and sinking 79uA.

Designed For:  
3.0Vout at 60Vin with 10uA draw.

▲ Enable is positive-logic. Pulled-up internally (do NOT connect external pull-up resistor). Will be on by default, ground if wanting to disable.

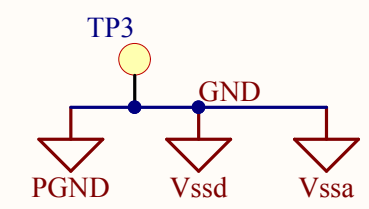
▲ Even though DC/DC converter is isolated, grounds are connected together.

▲ 10uF or higher. Not needed for DC/DC stabilization but needed for linear reg stabilization.



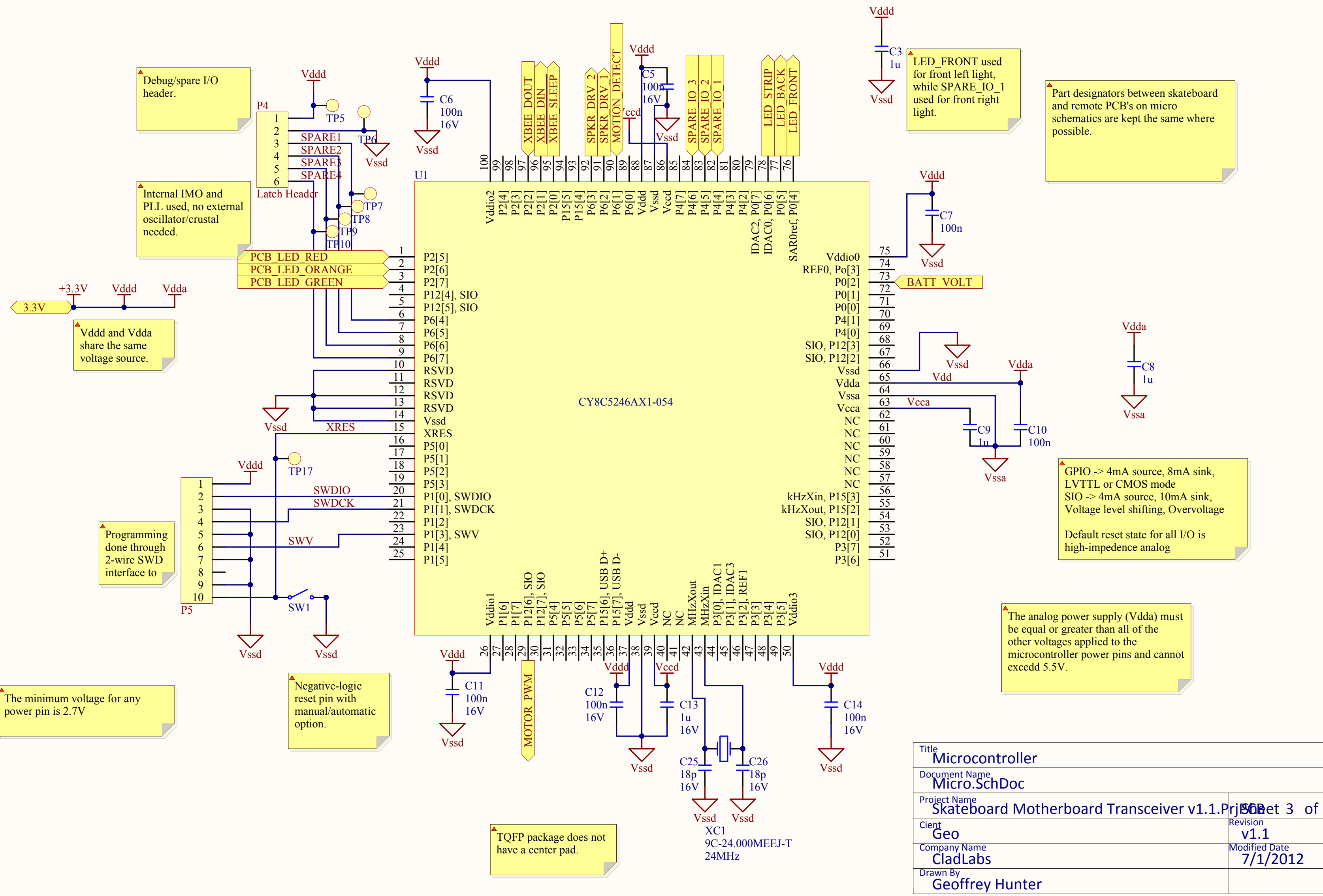
▲ 10uF input capacitance minimum for regulator stabilisation.

▲ Regulator drops 12V down to 3.3V for microcontroller and Xbee module.

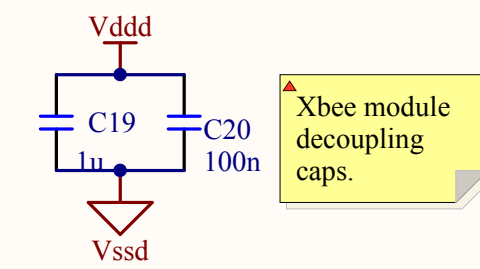
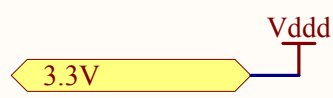


▲ Star-connection of grounds. Particular care to keep power ground seperated from the others because of motor.

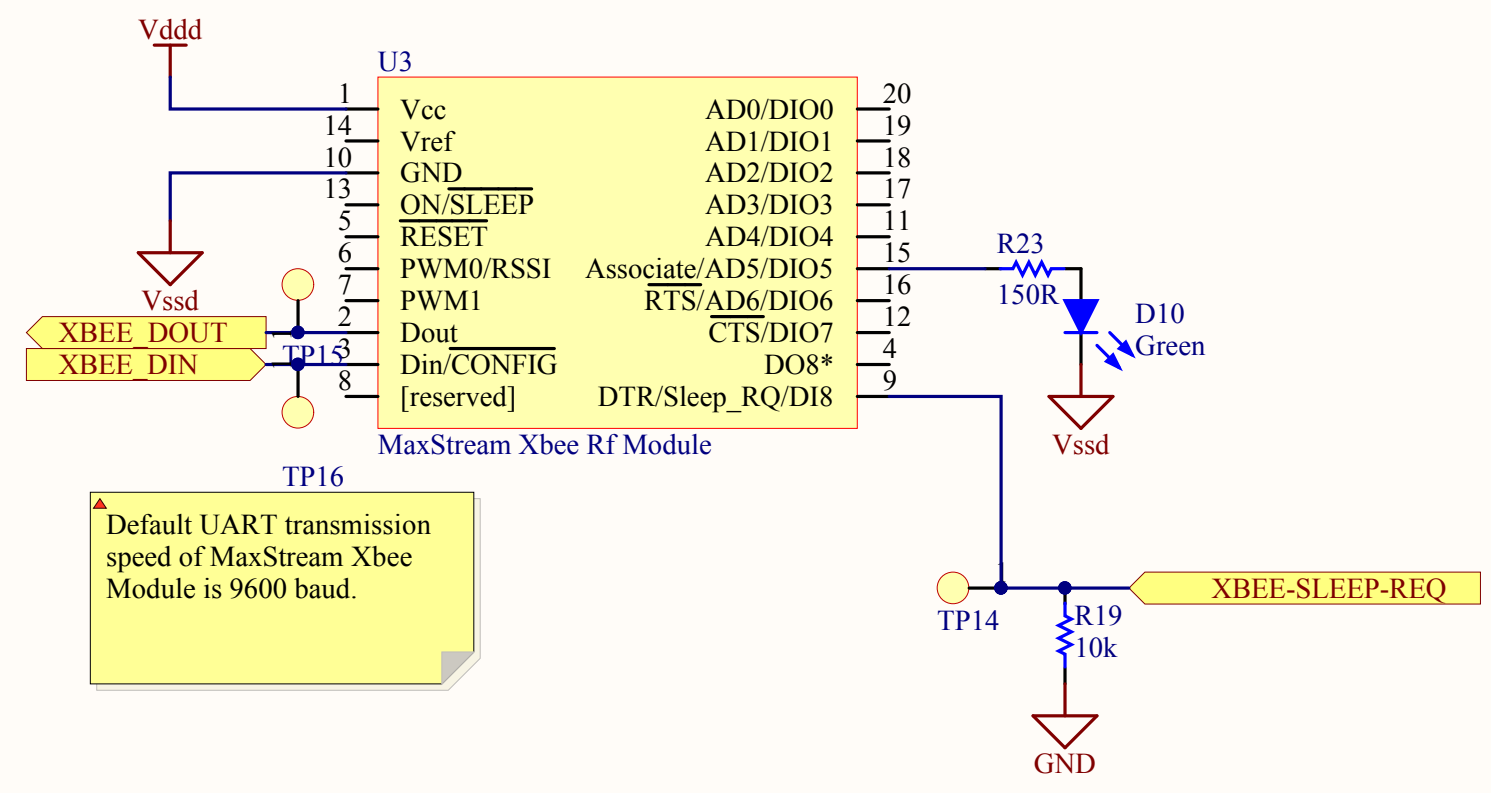
|   |                                  |
|---|----------------------------------|
| Title<br><b>Power Supply</b>  |                                  |
| Document Name<br><b>PSU.SchDoc</b>                                    |                                  |
| Project Name<br><b>Skateboard Motherboard Transceiver v1.1.PrjSCH</b> |                                  |
| Client<br><b>Geo</b>  | Revision<br><b>v1.1</b>          |
| Company Name<br><b>CladLabs</b>                                       | Modified Date<br><b>7/1/2012</b> |
| Drawn By<br><b>Geoffrey Hunter</b>                                    |                                  |



|   |                                  |
|---|----------------------------------|
| Title<br><b>Microcontroller</b>                                       |                                  |
| Document Name<br><b>Micro.SchDoc</b>                                  |                                  |
| Project Name<br><b>Skateboard Motherboard Transceiver v1.1.Prj506</b> |                                  |
| Client<br><b>Geo</b>  | Revision<br><b>v1.1</b>          |
| Company Name<br><b>CladLabs</b>                                       | Modified Date<br><b>7/1/2012</b> |
| Drawn By<br><b>Geoffrey Hunter</b>                                    |                                  |



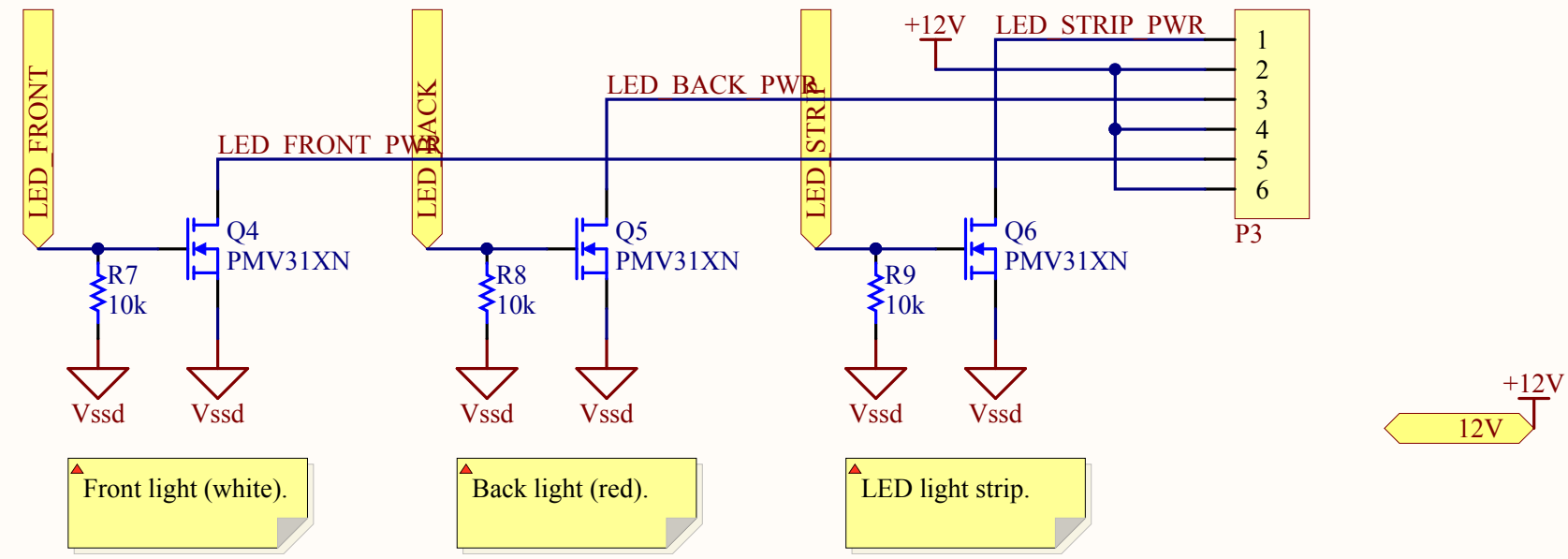
▲ Part designators between skateboard and remote PCB's on Xbee schematics are kept the same where possible.



|   |                                  |
|---|----------------------------------|
| Title<br><b>Xbee Communications</b>                                   |                                  |
| Document Name<br><b>Xbee.SchDoc</b>                                   |                                  |
| Project Name<br><b>Skateboard Motherboard Transceiver v1.1.Prj500</b> |                                  |
| Client<br><b>Geo</b>  | Revision<br><b>*</b>             |
| Company Name<br><b>CladLabs</b>                                       | Modified Date<br><b>7/1/2012</b> |
| Drawn By<br><b>Geoffrey Hunter</b>                                    |                                  |

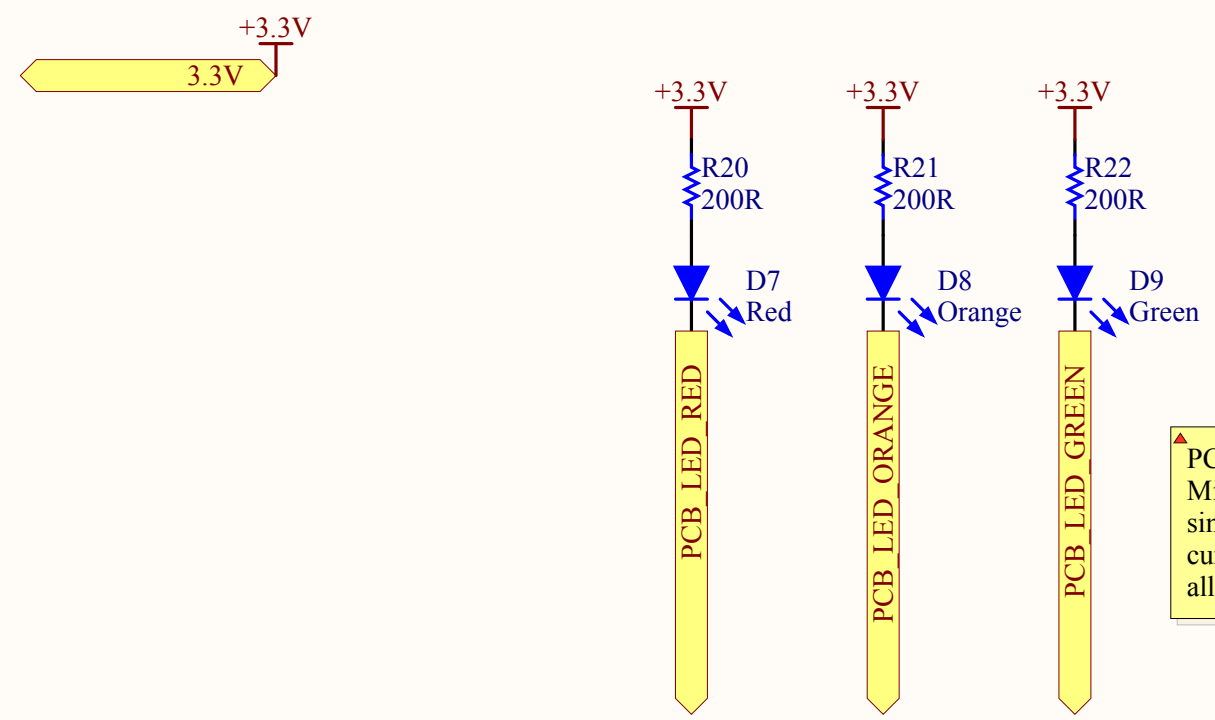
A

A



B

B



C

C

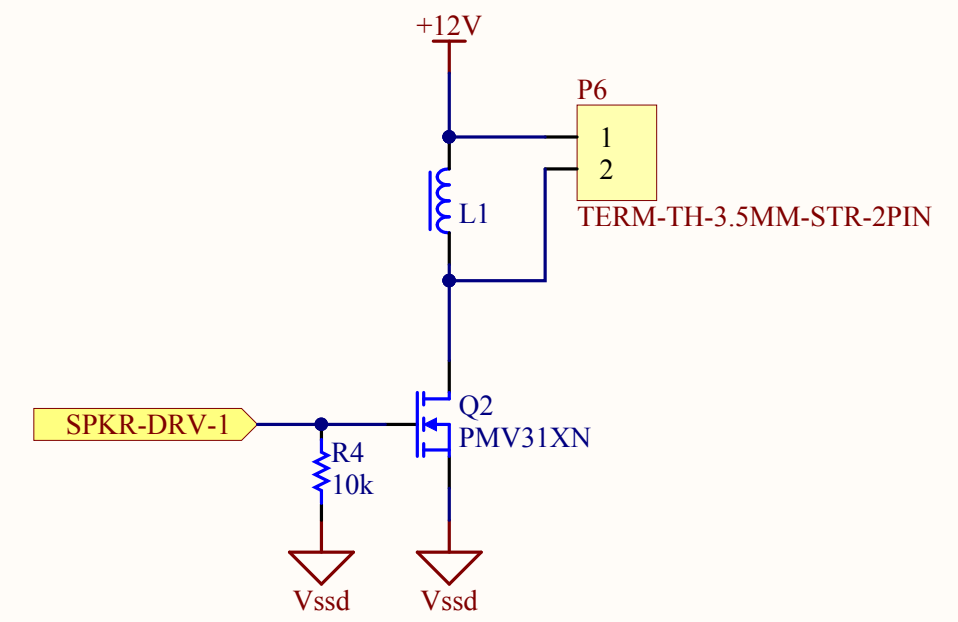
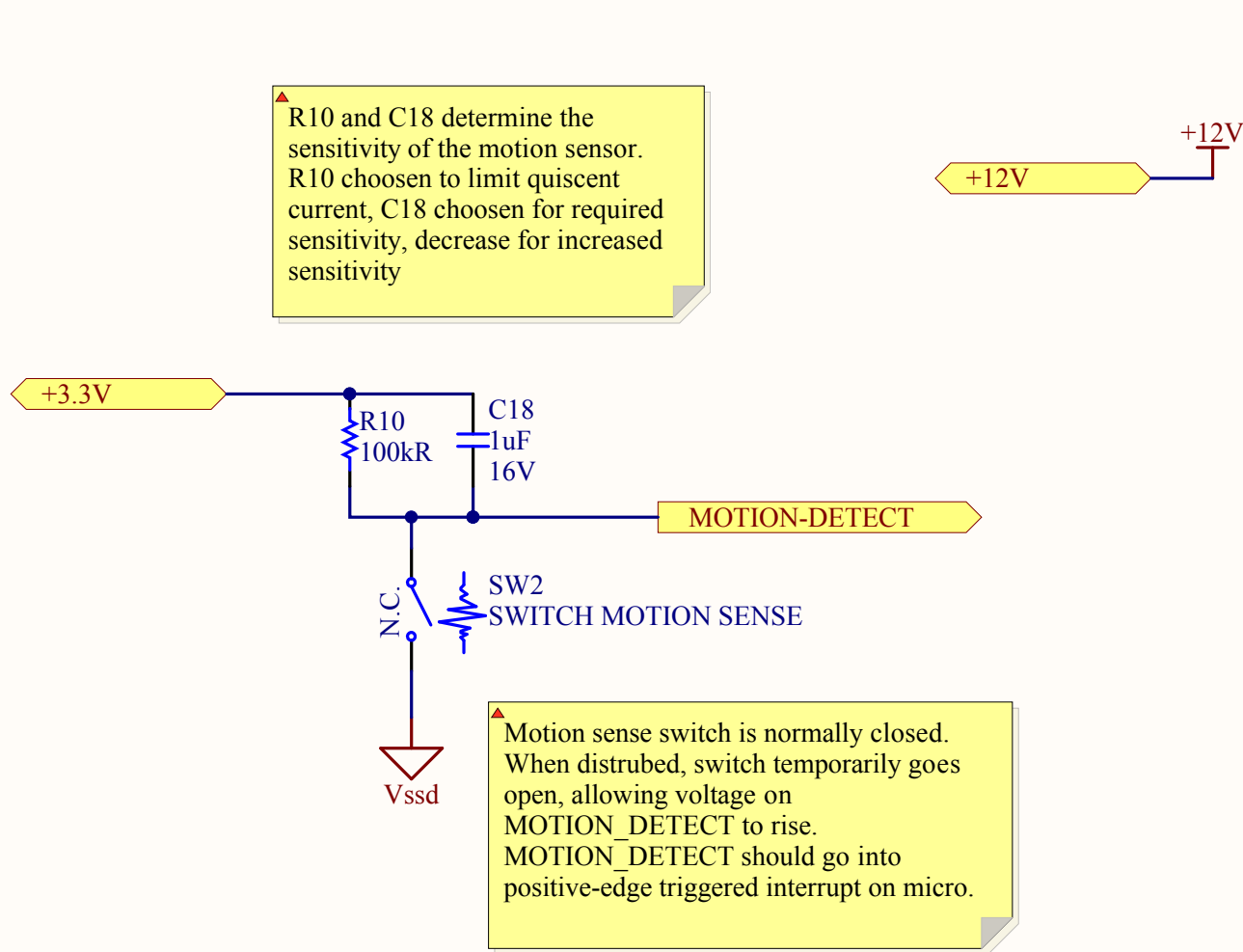
PCB LED's  
Micro directly  
sinks the LED  
current (up to 8mA  
allowed per pin).

Status LED's

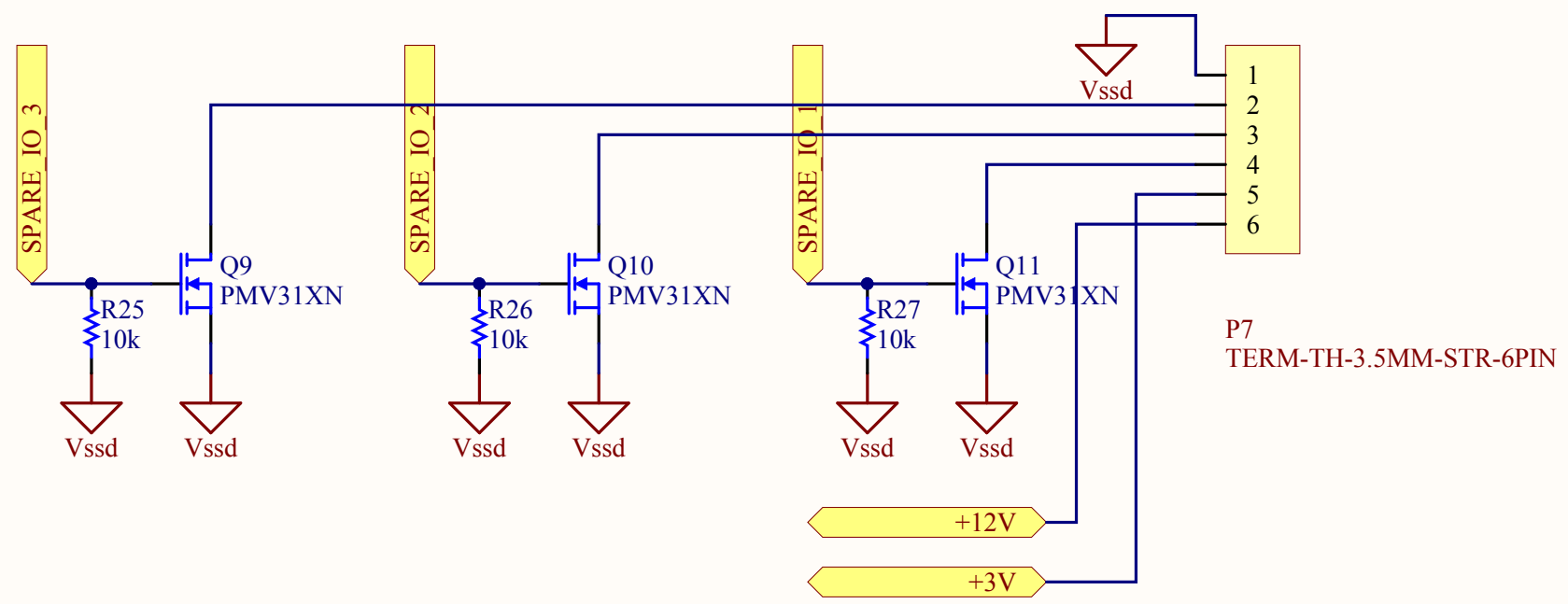
D

D

|   |  |
|---|--|
| Title<br><b>LED's</b>   |  |
| Document Name<br><b>LEDs.SchDoc</b>                                   |  |
| Project Name<br><b>Skateboard Motherboard Transceiver v1.1.Prj506</b> |  |
| Revision<br><b>v1.1</b>   |  |
| Client<br><b>Geo</b>  |  |
| Company Name<br><b>CladLabs</b>                                       |  |
| Drawn By<br><b>Geoffrey Hunter</b>                                    |  |
| Sheet 5 of 7  |  |
| Modified Date<br><b>7/1/2012</b>                                      |  |



|   |  |
|---|--|
| Title<br><b>Motion Alarm</b>  |  |
| Document Name<br><b>Motion Alarm.SchDoc</b>                           |  |
| Project Name<br><b>Skateboard Motherboard Transceiver v1.1.PrjSCH</b> |  |
| Revision<br><b>v1.1</b>   |  |
| Company Name<br><b>CladLabs</b>                                       |  |
| Modified Date<br><b>7/1/2012</b>                                      |  |
| Drawn By<br><b>*</b>  |  |



|   |  |
|---|--|
| Title<br><b>Spare I/O</b>   |  |
| Document Name<br><b>Spare IO.SchDoc</b>                               |  |
| Project Name<br><b>Skateboard Motherboard Transceiver v1.1.PrjSCH</b> |  |
| Revision<br><b>v1.1</b>   |  |
| Client<br><b>Geo</b>  |  |
| Company Name<br><b>CladLabs</b>                                       |  |
| Modified Date<br><b>7/1/2012</b>                                      |  |
| Drawn By<br><b>Geoffrey Hunter</b>                                    |  |

A

A

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B

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C

D

D